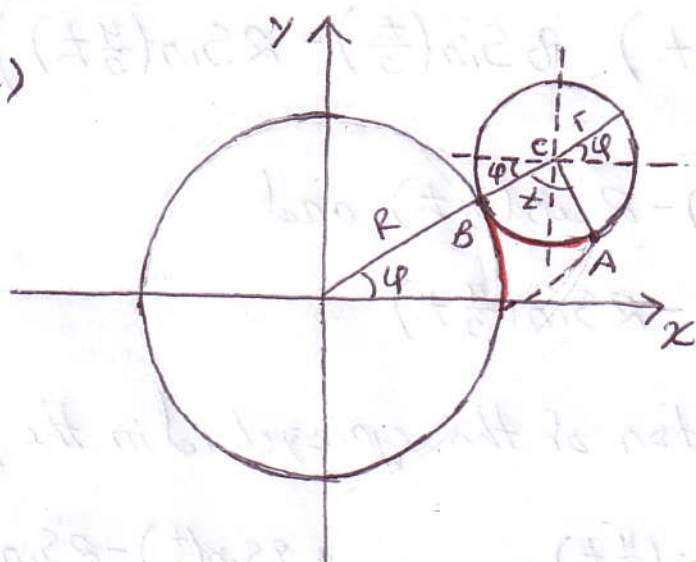


(1)

Solutions to Exam 2

1. a)



Let  $A$  be a fixed point  $t$  on the small circle and  $B$  be a point that will touch the bigger circle after the small circle rolled by an angle  $t$ . We need to determine  $A(t)$ .

Notice that  $A(t) = \vec{C} + \vec{AC}$  where

$$\vec{C} = (R+r)(\cos\varphi, \sin\varphi) \text{ and}$$

$$\vec{AC} = r(\cos(\pi + \varphi + t), \sin(\pi + \varphi + t)) \text{ (Why?)}$$

Observe that  $\varphi R = t r$  (why?) so  $\varphi = \frac{r}{R} t$ .

Therefore,

$$\vec{AC} = r\left(\cos\left(\pi + \frac{R+r}{R}t\right), \sin\left(\pi + \frac{R+r}{R}t\right)\right) = r\left(-\cos\left(\frac{R+r}{R}t\right), -\sin\left(\frac{R+r}{R}t\right)\right)$$

$$= \left(-r\cos\left(\frac{R+r}{R}t\right), -r\sin\left(\frac{R+r}{R}t\right)\right) \text{ and}$$

$$\vec{C} = \left([R+r]\cos\left(\frac{r}{R}t\right), [R+r]\sin\left(\frac{r}{R}t\right)\right)$$

Thus,

$$A(t) = \left([R+r]\cos\left(\frac{r}{R}t\right) - r\cos\left(\frac{R+r}{R}t\right), [R+r]\sin\left(\frac{r}{R}t\right) - r\sin\left(\frac{R+r}{R}t\right)\right)$$

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b) When  $R=6$  and  $r=2$ ,  $A(t)$  becomes

$$\left( 8 \cos\left(\frac{t}{3}\right) - 2 \cos\left(\frac{4}{3}t\right), 8 \sin\left(\frac{t}{3}\right) - 2 \sin\left(\frac{4}{3}t\right) \right)$$

c) Let  $s = 8 \cos\left(\frac{t}{3}\right) - 2 \cos\left(\frac{4}{3}t\right)$  and  
 $t = 8 \sin\left(\frac{t}{3}\right) - 2 \sin\left(\frac{4}{3}t\right)$

Then, the parameterization of this epicycloid in the plane is

$$(1, 2, 3) + \frac{8 \cos\left(\frac{t}{3}\right) - 2 \cos\left(\frac{4}{3}t\right)}{\sqrt{18}} (-1, 1, 4) + \frac{8 \sin\left(\frac{t}{3}\right) - 2 \sin\left(\frac{4}{3}t\right)}{\sqrt{2}}$$

$$(1, 1, 0).$$

2. a)  $f'(t) = (1, -4t, 3t^2)$

b)  $DF(t)$  is a function from  $\mathbb{R}$  to  $\mathbb{R}^3$ . For fixed  $t$ ,  $DF(t)$  is a linear map.

$$DF(t)(s) = (s, -4ts, 3t^2s), \text{ where } s \in \mathbb{R}.$$

In other words,  $f'(t)$  is the velocity vector, while  $DF(t)$  is the tangent line.

3. a) She should move in the direction of the gradient at  $(0, 1)$ ,  $\nabla f(0, 1)$ .

$$\text{Now } \nabla f(x, y) = (-6x, -2y). \text{ Therefore, } \nabla f(0, 1) =$$

$= (0, -2)$ . Hence, the direction in which the woman should

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move is given by  $u = \frac{(0, -2)}{\|(0, -2)\|} = \frac{(0, -2)}{2} = (0, -1)$ .

b) The woman cannot move in a direction steeper than 1. Suppose that she moves at an angle  $\theta$  to the gradient. Then  $D_u f(0, 1) = \|\nabla f(0, 1)\| \cos \theta \leq 1$ . Since  $\|\nabla f(0, 1)\| = 2$ , the maximal allowed steepness is achieved when  $2 \cos \theta = 1$ , which happens when  $\theta = \frac{\pi}{3}$  or  $\theta = -\frac{\pi}{3}$ . Thus, the two possible solutions are

$$(1) \left( -\frac{\sqrt{3}}{2}, -\frac{1}{2} \right)$$

$$(2) \left( \frac{\sqrt{3}}{2}, -\frac{1}{2} \right)$$

$$4. J(f \circ g \circ h)(1, 0) = Jf(g \circ h(1, 0)) Jg(h(1, 0)) Jh(1, 0)$$

$$a) \text{ Since } h(1, 0) = (1, 1), g(h(1, 0)) = g(1, 1) = (0, 2, 1),$$

$$\text{we see that } J(f \circ g \circ h)(1, 0) = Jf(0, 2, 1) Jg(1, 1) Jh(1, 0) =$$

$$= \begin{pmatrix} 0 & 4 & 0 \\ 3 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} 12 & 4 \\ 3 & 3 \end{pmatrix}$$

$$b) D(f \circ g \circ h)(1, 0)(u, v) = (12u + 4v, 3u + 3v)$$

5. Let  $f(x, y, z) = xyz$  be subject to the constraint

S. then  $z$  is not independent of  $x$  and  $y$ . That is

$$z = z(x, y). \text{ Therefore } \frac{\partial f}{\partial x} \Big|_S = \frac{\partial}{\partial x} (xyz(x, y))$$

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Now  $\frac{\partial}{\partial x}(xyz(x,y)) = yz + xy \frac{\partial z}{\partial x}$ , where  $\frac{\partial z}{\partial x}$  can be computed by taking the partial derivative of  $x^4 + y^4 + z^4 = 1$  with respect to  $x$ .

$$\frac{\partial}{\partial x}(x^4 + y^4 + z^4) = \frac{\partial}{\partial x}(1) \text{ or}$$

$$4x^3 + 4z^3 \frac{\partial z}{\partial x} = 0 \text{ Hence } \frac{\partial z}{\partial x} = -\frac{4x^3}{4z^3} = -\frac{x^3}{z^3}.$$

With this result, we see that

$$\frac{\partial}{\partial x}(xyz) = yz + xy \frac{\partial z}{\partial x} = yz - \frac{x^4 y}{z^3}$$

To compute  $\frac{\partial f}{\partial x} \Big|_S(0,0,1)$ , just replace these values in place of  $x, y$ , and  $z$ :  $0 \cdot 1 - \frac{0^4 \cdot 0}{1^3} = 0$ .

6. We wish to minimize  $x^2 + y^2 + z^2$  under the constraint

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1 \text{ or } x^2 = a^2 \left(1 - \frac{y^2}{b^2} - \frac{z^2}{c^2}\right).$$

$$\text{Let } f(y, z) = y^2 + z^2 + a^2 \left(1 - \frac{y^2}{b^2} - \frac{z^2}{c^2}\right)$$

$$\text{Now } \nabla f(y, z) = \left(2y - 2\frac{a^2}{b^2}y, 2z - 2\frac{a^2}{c^2}z\right) = (0, 0).$$

The only solution is  $(y, z) = (0, 0)$  (because  $\frac{a^2}{b^2} \neq 1$ ).

$$\text{Now } H_f(y, z) = \begin{pmatrix} 2 & 0 \\ 0 & 2\frac{c^2 - a^2}{c^2} \end{pmatrix} \text{ is positive-}$$

definite. Therefore  $f$  attains its minimum when

$x^2 = f(0, 0) = a^2$ . Hence the closest points on the ellipsoid

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are  $(-a, 0, 0)$  and  $(a, 0, 0)$ ,

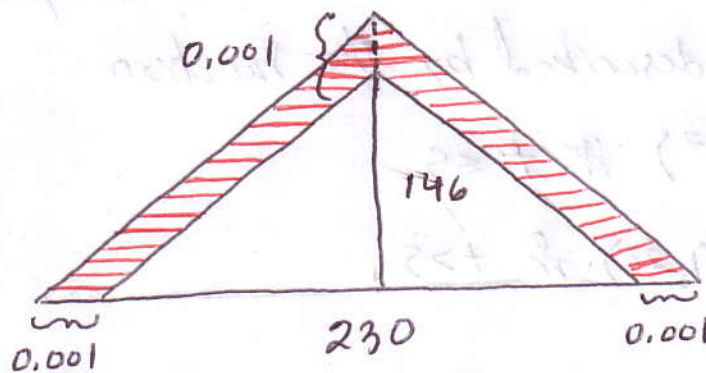
7. Let  $g(x) = \sin(x)$  and  $T(x, y) = 3x + 2y$

Then  $f = g \circ T$  where  $T$  is linear. Therefore, if  $p(x)$  is the third-degree Taylor polynomial of  $g$ ,  $p \circ T$  is the third-order Taylor polynomial of  $f$ .

Now since the third-degree Taylor polynomial of  $g(x) = \sin(x)$  is  $p(x) = \sum_{n=0}^3 \frac{(-1)^n x^{2n+1}}{(2n+1)!}$ , the third-order Taylor

polynomial of  $f$ ,  $P(x, y) = \sum_{n=0}^3 \frac{(-1)^n (3x+2y)^{2n+1}}{(2n+1)!}$

8.



$$V = \frac{1}{3} h b^2$$

$$dV = \frac{\partial V}{\partial h} (146, 230) \cdot 0.001 + 2 \frac{\partial V}{\partial b} (146, 230) \cdot 0.001 =$$

$$= \left( \frac{\partial V}{\partial h} + 2 \frac{\partial V}{\partial b} \right) 0.001 = \left( \frac{1}{3} b^2 + \frac{4}{3} h b \right) \cdot 0.001 =$$

$$= \frac{0.001}{3} (b^2 + 4hb) = \frac{0.001}{3} 230 (230 + 4 \cdot 146) \approx 62.4$$

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Thus,  $62.4 \text{ m}^3$  of gold was used.

$$9. \quad \frac{\partial u}{\partial t} = sf(s+e^t, s-e^{-2t}) + ts \left( \frac{\partial f}{\partial x}(s+e^t, s-e^{-2t})e^t + \frac{\partial f}{\partial y}(s+e^t, s-e^{-2t}) \cdot 2e^{-2t} \right)$$

$$10. \quad \text{Let } u = (x^2 + 2y). \quad \text{Then } \sin u = \sum_{n=0}^{\infty} \frac{(-1)^n u^{2n+1}}{(2n+1)!} = \\ = \sum_{n=0}^{\infty} \frac{(-1)^n (x^2 + 2y)^{2n+1}}{(2n+1)!}$$

11. To arrive at the space station, you must first travel along the parabolic path and then release the pod for docking. Thus, your path is described by the function

$$p(t) = \begin{cases} (t, t^2) & \text{if } t \leq s \\ (s, s^2) + (t-s)(1, 2s) & \text{if } t > s \end{cases}$$

where  $s$  is the time when the pod is released.

Notice that docking takes place when  $p(t) = g(t)$  or  $(s, s^2) + (t-s)(1, 2s) = (4 + \cos(\frac{\pi}{8}t), 8 - \sin(\frac{\pi}{8}t))$

This equation reduces to

$$t = 4 + \cos\left(\frac{\pi}{8}t\right)$$

$$2st - s^2 = 8 - \sin\left(\frac{\pi}{8}t\right)$$

Although the equation  $t = 4 + \cos\left(\frac{\pi}{8}t\right)$  is difficult to solve

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Systematically, notice that when  $t=4$ ,  $4 + \cos\left(\frac{\pi}{8} \cdot 4\right) = 4 + \cos\left(\frac{\pi}{2}\right) = 4$ . Therefore  $t=4$  is a solution.

When  $t=4$ , the equation

$$2st - s^2 = 8 - \sin\left(\frac{\pi}{8}t\right)$$

becomes

$$8s - s^2 = 7$$

which reduces to

$$(s-1)(s-7) = 0$$

Since  $s < t=4$ ,  $s=1$  is the only solution.

Hence the pod should be released 1 year into the journey.

The pod will then float through space for additional 3 years before docking with the space station.

12. Let  $u(x) = \int_0^x g(s) ds$  and  $v(x) = x$ . Then

$$F(x) = \int_0^{u(x)} f(v(x), t) dt.$$

If we define  $T(u, v) = \int_0^u f(v, t) dt$  and  $S(x) = (u(x), v(x))$ ,

then  $F(x) = T(S(x))$ . Hence,

$$\frac{dF}{dx} = \frac{\partial T}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial T}{\partial v} \frac{\partial v}{\partial x} = f(v(x), u(x)) \cdot u'(x) + \int_0^{u(x)} \frac{\partial f}{\partial x}(v(x), t) dt.$$

$$\cdot v'(x) = f\left(x, \int_0^x g(s) ds\right) g(x) + \int_0^{\int_0^x g(s) ds} \frac{\partial f}{\partial x}(x, t) dt.$$